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HELD: Hierarchical Entity-Label Disambiguation in Named Entity Recognition Task Using Deep Learning

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21	Abstract. Named Entity Recognition (NER) is a challenging learning task of identifying and classifying entity mentions in
22	texts into predefined categories. In recent years, deep learning (DL) methods empowered by distributed representations, such as word, and character-level embeddings, have been employed in NER systems. However, for information extraction in Police par-
23	rative reports, the performance of a DL-based NER approach is limited due to the presence of fine-grained ambiguous entities.
24	For example, given the narrative report "Anna stole Ada's car", imagine that we intend to identify the VICTIM and the ROB-
25	BER, two sub-labels of PERSON. Traditional NER systems have limited performance in categorizing entity labels arranged in a hierarchical structure. Furthermore, it is unfeasible to obtain information from knowledge bases to give a disambiguated
26	meaning between the entity mentions and the actual labels. This information must be extracted directly from the context de-
27	pendencies. In this paper, we deal with the Hierarchical Entity-Label Disambiguation problem in Police reports without the
28	NER: a BLSTM-CRF architecture and a NER tool. Experiments conducted on a real Police reports dataset show that HELD
29	significantly outperforms baseline approaches.
30	Keywords: Fine-grained entity labels, Hierarchical Entity-Label Disambiguation using Context, Named Entity Recognition,
31	Deep Learning, Police reports domain
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36	1. Introduction
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38	Named Entity Recognition (NER) is a challenging learning task of identifying named-entity mentions

³⁸ in texts and classifying them into predefined categories, such as person, location, and organization. NER
 ³⁹ is an essential task for a variety of Natural Language Processing (NLP) applications, such as topic de ⁴⁰ tection and speech recognition. Early NER systems often require significant human effort in carefully
 ⁴¹ designing rules or features. This trend has motivated the use of deep learning (DL) in NER over the past
 ⁴² few years due to requiring minimum feature engineering. Besides, DL-based NER approaches have been
 ⁴³ empowered by distributed representations, which consider word- and character-level embeddings as well

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as the incorporation of additional features like orthographic features and language-specific knowledge resources, such as gazetteers [1]. However, language-specific resources and features are costly to develop, especially for new languages and new domains, making NER a challenge to adapt [2].

Furthermore, traditional NER tasks focus on a specific set of entity labels and one label per named entity. For relation extraction in domain-specific applications, it is more useful to work with an authentic set of fine-grained labels for the domain [3, 4]. Typically, fine-grained NER tasks focus on a larger number of entity labels arranged in a hierarchical structure, where an entity mention can be assigned to multiple labels. In the attempt for finer granularity, complex knowledge bases have been used to leveraged NER models [5]. Existing systems first extract the entity mentions and then link the mentions to one or more referent entities in a knowledge base [6–8]. Such ability can be performed by Named Entity Disambiguation (NED) methods. For example, given the sentence "Paris is the capital of France", NER would pass the mentions of Paris and France to the NED stage, which would identify Paris as the capital city of France and not as something else as a building or even a person (e.g., the businesswoman Paris Hilton). Within this context, Paris is a CAPITAL_CITY, a sub-label of CITY, which, in turn, is a sub-label of LOCATION. If a knowledge base has these three matching labels, all of them must be assigned to *Paris*. The knowledge bases for NED are commonly derived from Wikipedia, YAGO, or a complex combination of several resources, including, among others, WordNet and Wiktionary [6-8], or by using linked datasets [9].

However, not all domains have well-defined knowledge bases that provide a background repository to fine-grained named entity disambiguation. For instance, in the Police reports domain, it is impractical to have a knowledge base that describes previously some details about all incidents, such as knowing 2.2 from the persons involved who is the victim, witness, robber, etc. Besides, each case must be analyzed individually. Consider a part of a real Police narrative report: "The above-qualified declarant stated that her sister Augusta Dias was beaten and had her car stolen on the day, place, and time mentioned above. The declarant informs that the author was a person known as Augus. Augusta was seriously injured at the incident location. With nothing else to declare."¹ Imagine that we intend to identify in the text the VICTIM and the ROBBER, two sub-labels of PERSON. Notice that our objective of recognizing the mentions of Augusta Dias and Augusta as the VICTIM and Augus as the ROBBER is very challenging since both names preserve the same orthographic features. It is unfeasible to derive the information that someone is a VICTIM or a ROBBER from Wikipedia, YAGO, or by using linked datasets as done in previous works [7–9]. Therefore, this information must be extracted from the context dependencies.

In this work, we deal with the Hierarchical Entity-Label Disambiguation problem in Police reports. Our proposed solution, called HELD, enhances a state-of-the-art NER tool by using an ensemble archi-tecture and is a domain-independent approach (i.e., it can be used by various real-world applications or even by NER systems in general domain). We build HELD to be free from knowledge bases, language-specific resources (e.g., gazetteers, word clusters id, and part-of-speech tags), or hand-crafted features (e.g., word spelling and capitalization patterns). HELD is an ensemble model that combines two se-quence labeling components for NER: a bidirectional Long-Short Term Memory neural network with a subsequent Conditional Random Field decoding layer (BLSTM-CRF) and an off-the-shelf NER tool from the spaCy library, to learn from the context how to disambiguate fine-grained entity labels.

⁴¹ As stated in [1], there are some strengths of why using DL architectures for the NER task, which ex-⁴² plain the considerable number of studies that applied DL-based NER systems and successively advanced ⁴³ the state-of-the-art performance. The same motivations are considered for this work. First, compared to

¹For reasons of confidentiality and preservation of those involved, the names mentioned in the narrative are fictitious.

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feature-based approaches, deep learning is beneficial in discovering hidden features automatically. DL-based models use non-linear activation functions to learn complex features from raw data. In fact, the Hierarchical Entity-Label Disambiguation problem corresponds to a non-linear transformation between the input and output. Second, DL-based models can learn useful representations and underlying pat-terns from Police reports, saving significant effort in designing features to perform fine-grained label disambiguation. Several approaches propose NER models derived from LSTM [10–12], by combining BLSTM with CNNs [13] or by solving the problem of word disambiguation [14]. None of these works solves the label disambiguation problem given an input text without the use of knowledge bases. Current fine-grained NER systems also leveraged their models and automatically annotate training corpora with over a hun-dred labels via knowledge base lookup [3, 15–18]. In [19], the HYENA model performs a top-down hierarchical fine-grained label classification based on an extrinsic study with a NED tool, however, the authors build a set of classifiers that mark entity mentions connected to a knowledge base. Re-cently, BERT [20] is becoming a new paradigm for NER task as proposed in [21–24]. While in practice, BERT and other contextualized language-model embeddings [25–27] have a prohibitively large number of parameters, require a massive amount of training data and powerful computing resources to ensure promising results for a specific language or domain. Due to the limitation of an available huge dataset of annotated Police reports, we will investigate language models to our problem as future work. The contributions of this paper are as follows: 2.0 (1) We introduce a formalization of the Hierarchical Entity-Label Disambiguation problem in Police reports. The formalization defines the hierarchical structure present in the fine-grained named 2.2 entities of Police reports. (2) We propose and developed HELD, an ensemble and domain-independent approach that extends a pre-trained NER tool from the spaCy library and a BLSTM-CRF model to solve the Hierarchical Entity-Label Disambiguation problem in Police reports without the use of knowledge bases. (3) We explore some different approaches for coping with the data imbalance problem present in a real-world manually annotated dataset for the Police domain. (4) An in-depth study to provide the best word-level representation (pre-trained or domain-specific), that most effectively represent the Police report's vocabulary, for one of the main components in HELD. (5) An extensive experimental evaluation over a real-world dataset, where we assess the validity of HELD in terms of quality of results. Our proposal can surpass F₁-score comparing to baseline approaches. The remainder of this paper is organized as follows. Section 2 reviews related works. Section 3 pro-vides the problem definition. Section 4 presents the methodological details of HELD. Section 5 presents the experiments and discusses the experimental evaluation. Finally, Section 6 summarizes this work and discusses future directions. 2. Related Work Several works have presented models that use well-formatted documents heavily depend on a phrase's local linguistic features, such as capitalization, part-of-speech (POS) tags of previous words, external resources, such as gazetteers, or large dictionaries of entities gathered from Freebase, Wikipedia, and

YAGO, to perform NER and NED tasks [6–8, 28–31]. Other examples include current works that deal with a hundred fine-grained entities that also use knowledge bases to leverage their models, such as automatically annotate training corpora [3, 15–18]. In recent years, deep learning models have attracted attention to solving NER tasks due to require minimal feature engineering, as stated in [1] that reviews the literature based on varying deep learning models for NER.

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Apart from the English language, there are many studies on the classification of named entities in documents written in other languages or cross-lingual setting. For example, [32] investigated a deep learning method to recognize clinical entities in Chinese clinical documents using the minimal feature engineering approach. In [33], the authors incorporated dictionaries into deep neural networks for the Chinese named entity recognition task. In addition to Chinese, there also exist studies that have been conducted for named entity detection in documents in other languages. Examples include Portuguese [34], and Japanese [35]. Each language has its characteristics for understanding the fundamentals of the NER task for that language, which makes NER models very challenging to adapt.

Many studies as [36, 37] use a self-attention mechanism to the neural architecture to solve the NER problem in a cross-lingual setting by transferring knowledge from a source language to a target language with few or no labels. Another interesting work is [38], which examines the effects of transfer learning for deep hierarchical recurrent networks across domains, applications, and languages, showing that sig-nificant improvements can often be achieved in several tasks, including NER. There has also been a long history of research involving neural networks for entity recognition in documents, even with fine-grained entities. [11] attempted NER with a single direction LSTM network. The work [10] proposes two neural architectures for sequence labeling: one based on bidirectional LSTMs and a CRF model, and the other that constructs and labels segments using a transition-based approach inspired by shift-reduce parsers.

Similarly, [13] and [39] combine bidirectional LSTM with CNNs, while [40] re-implemented the NER model described by [39], adjusting it to work with fine-grained labels for the English language. For Japanese, [40] removed the CNN layer, which previously learns character-level embeddings, to use dictionary (gazetteer feature) and category embeddings. [16] use an LSTM to encode the fine-grained entity mentions representations and a bidirectional LSTM as context encoder, and perform a feature and model level transfer learning. [18] combining token embeddings from the ELMo contextualized lan-guage model [25], which are fed into a residual LSTM module, to finally pass the detected entities into the Wikidata knowledge base. [41] uses a CNN over a sequence of word embedding with a CRF on the top. [34] is based on the CharWNN deep neural network, which uses word and character embeddings to perform sequential classification. [14] addresses an orthogonal problem called word sense disambigua-tion problem. Its contribution consists of models from a traditional LSTM-based model, a variant that incorporates an attention mechanism and an encoder-decoder architecture.

Recently, the contextualized language models, such as BERT, GPT [26], ELMo, and Flair Embeddings [27], are becoming a new paradigm of NER. BERT, which uses the Transformer architecture [42], among with its derived models, such as RoBERTa [43] and Albert [44], is one of the most adopted models. Some works have achieved promising performance via leveraging the combination of traditional embeddings (e.g., Google Word2Vec, Stanford GloVe, etc.) and BERT or by fine-tuning BERT with one additional output layer for the NER task as [21–24]. However, BERT has a prohibitively large number of parameters and require substantial computational resources [45]. Besides, even though the Transformer encoder is more effective than LSTM, it fails the NER task if they are not pre-trained, and when training data is limited [1]. The pre-trained contextualized embeddings are data-hungry and require a massive amount of training data to be fine-tuning for a domain-specific NER task. Due to this limitation, we will jointly investigate our approach with the pre-trained language models in future works.

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It is worth mentioning that none of the previously mentioned related works address our problem. The problem addressed by [19] solved by the HYENA model is adjacent to the Hierarchical Entity-Label Disambiguation problem. Different from HELD in practice, HYENA is a representative supervised method that uses a top-down hierarchical classifier. Its features include the words in the named entity mention, in sentence and paragraph, and POS tags. It performs basic co-reference resolution and marks entity mentions connected to the fine-grained labels present in the YAGO knowledge base.

In our previous work [46], we also tackle a quite similar problem, i.e., the label or class disambiguation in Police reports documents. We proposed a Char-BLSTM-CRF model that concatenates char and word embeddings to combine word- and character-level representations to feed them into BLSTM to model context information of each word. On the top of BLSTM, there is a sequential CRF to decode labels for the whole sentence jointly. In this paper, we propose HELD, an ensemble model that com-bines a variation of Char-BLSTM-CRF to enhance an off-the-shelf NER tool to solve the Hierarchical Entity-Label Disambiguation problem in Police reports. Compared to existing works in the literature, we highlight that our approach does not rely on knowledge bases to disambiguate the entities present in the text. This brings advantages to HELD in several domains where it is unfeasible to create knowledge bases to support NER tasks, such as in the Police domain.

3. Problem Definition

In this section, we introduce the formulation of our Hierarchical Entity-Label Disambiguation problem in Police reports, and some basic concepts and notations used throughout the paper. A Police narrative report is a document that describes all of the raised facts, circumstances, and timeline events surrounding an incident. The process of writing and the protocols applied to the Police reports might vary from one agency to another, however, the general information and function are relatively the same.

A challenge to automate the information extraction from such a document is the correct interpretation of the domain-specific named entities according to their roles in the narrative. In literature, NER is the task to identify entity mentions from text belonging to predefined categories, such as person, location, and organization, which define the well-known generic category of entity labels. In order to intelligently understand different texts and extract a wide range of information, it is useful to precisely determine the labels of entity mentions for domain-specific NER systems. Thus, for our Police reports domain, the entity labels may reflect the victim, robber, witness, etc.

³³ Specifically, the entity recognizer for our Police domain must categorize the entities into fine-grained ³⁴ labels. This kind of NER task is called as fine-grained NER, which allows one entity mention to have ³⁵ multiple labels. Together, these labels constitute a path in a given label hierarchy, depending on the ³⁶ local context (i.e., the sentence context). The formal definitions of named entities and fine-grained entity ³⁷ labels in Police reports are as follows:

Definition 1. (Named Entities): The named entities are the real-world objects written in the narrative
 reports, represented by words or phrases that serve as a name for something or someone.

Definition 2. (Fine-Grained Entity Labels): The fine-grained entity labels are the roles or specializa tion of the named entities present in the narrative reports (e.g., victim, witness, incident location, etc.),
 organized in a hierarchy (e.g., victim is a sub-label of person and incident location is a sub-label of
 location).

In particular, when dealing with Police reports, it is crucial to avoid misunderstandings between the fine-grained entities. Most of them are proper nouns or terms often ambiguous. For example, the actual victim can not be recognized as the robber, and vice-versa. The same is also true for entities concerning the locations of the events present in the reports: the location of the incident should not be classified as the victim's residence location. The lack of a knowledge base to give a disambiguated meaning to entity mentions in the narratives increases the complexity of the problem. Consequently, it requires to perform the disambiguation of these named entities based on the context.

Recognize and disambiguate named entities is still a limitation to a NER-based approach, especially
 for the categorization of fine-grained entity labels. Thus, the problem that we want to solve here is to
 classify the named entities present in the Police reports according to their entity labels, arranged in a
 hierarchical structure. For this task, the classifier needs to solve the label disambiguation problem when
 assigning the proper role of the existing entities. Therefore, we define our Hierarchical Entity-Label
 Disambiguation problem:

Problem Statement. (Hierarchical Entity-Label Disambiguation using Context): We consider a variable-length sequence of input symbols $s = \{x_1, x_2, \dots, x_N\}$, and we aim to predict a sequence of output symbols $y = \{y_1, y_2, \dots, y_{N'}\}$. Input symbols are word tokens drawn from a given vocabulary V. Output symbols are labels drawn from a given set of fine-grained entity labels $L = \{l_1, l_2, \dots, l_C\}$ organized in a hierarchy of two or more levels, where C is the total number of labels. The top-level of this hierarchy consists of the super-labels E. Consider that L might present labels that are ambiguous for a given super-label $e_z \in E$. The problem tackled in this paper is to deal with the fine-grained entity labels disambiguation by regarding the sentence context. 2.2

In practice, to solve the Hierarchical Entity-Label Disambiguation problem, we consider for the ex-perimental procedures that our fine-grained entity labels are arranged in a two-level label hierarchy. The first level corresponds to generic super-labels, whereas, the second level contains fine-grained entity labels for the Police domain. For instance, named entities such as the victim's name and the robber's name should be assigned labels of type VICTIM and ROBBER, respectively. Also, both VICTIM and ROBBER entity labels correspond to only one super-label, in this case, PERSON. We will present and discuss further below in the next sections on this hierarchical structure present in the fine-grained labels of our domain.

4. HELD: A Method for Hierarchical Entity-Label Disambiguation in Police Reports

³⁵ In this section, we present HELD from bottom to top, characterizing the layers of the architecture. ³⁶ HELD is an ensemble approach designed to solve the Hierarchical Entity-Label Disambiguation problem ³⁷ in Police reports. Although the problem definition and our method were developed within the context of ³⁸ narrative reports, HELD is a domain-independent approach that can be applied to texts from different ³⁹ domains. As defined in the previous section, these texts must have ambiguous fine-grained entity labels ⁴⁰ organized in a hierarchy.

Refer to Figure 1 for an example illustration that provides an overview of HELD. Overall, given an input sentence $s = \{x_1, x_2, \dots, x_N\}$ that contains the individual words of a Police report drawn from a vocabulary *V*, the sequence of words *s* is used as input for two sequence labeling components for NER: a deep learning model, and a NER tool, that also uses DL-based methods. The Disambiguation Mask component combines the predictions of the two main components to tags each symbol $x_i \in V$

with an output symbol y_i. Specifically, the first two components in our approach are a NER model from
 the spaCy library and a BLSTM-CRF model. SpaCy has an off-the-shelf NER tool frequently used by
 academia and industry projects, while the BLSTM-CRF is the most common architecture for NER using
 deep learning [1]. We provide more details about the HELD components in the next sections.



Fig. 1. The overall architecture of HELD. An illustrative sentence is provided as input to the two main components of HELD: the NER component and the BLSTM-CRF component. For this example, the named entities we are interested in are: Anna, Ada, and Paris. All entities preserve the same orthographic features but observe that Paris is mentioned twice in different contexts. At first, it indicates Anna's residence, and, finally, the place where the incident occurred. The NER component recognizes the entities with the two super-labels PER (PERSON) and LOC (LOCATION). From the BLSTM-CRF component, we obtain the Probability Distribution of the Fine-Grained Labels. The output of the two components is used to feed into the Disambiguation Mask, which is the ensemble method that disambiguates the meaning. The final model output contains each sentence token assigned with its label: (i) Anna is the person involved in the incident; (ii) the first occurrence of Paris indicates that it is a residence location; (iii) Ada is the victim; and (iv) the second occurrence of Paris is the incident location.

As illustrated in Figure 1, HELD must intrinsically extract information from the context. One may think HELD could use OSM² as a knowledge base or GeoNames³ gazetteer to disambiguates the fine-grained entity labels related to the LOCATION super-label. However, OSM or GeoNames would not be applicable for other inherent entity labels in the Police domain (e.g., people present in the incident, such as the victim, robber, witnesses, among others). Another idea that comes up to help in the annotation pro-cess is a domain expert to supervise the entire learning process. This is similar to our previous work [47] called HNERD, which is an interactive framework designed to assist the user in the human annotation process and to perform NER tasks. In experimental procedures, we use HNERD to manually annotate a Police corpus. All in all, HELD is already effective in automatically learning useful representations and underlying factors from raw data.

²https://wiki.openstreetmap.org/wiki/Main_Page/

⁴⁵ ³https://www.geonames.org/

4.1. Named Entity Recognition Component

In our proposed ensemble model, the NER component is the one in charge of recognizing the named entities in Police reports into the top-level labels of the hierarchical structure present in our fine-grained entity labels. This component does not disambiguate the fine-grained entities. Instead, it identifies and classifies the entities belonging to the super-labels by performing a traditional sequence labeling NER task. Particularly in our context, we are interested in the recognition of two main types: LOCATION and PERSON. Afterward, the output of this component, jointly with the BLSTM-CRF output, will feed into the Disambiguation Mask.

We use spaCy NER⁴ as the NER component. This off-the-shelf NER tool is frequently awarded in many industry projects, given your sophisticated neural network-based model that achieves state-of-theart performance. In the latest release, spaCy v2.0's deep learning models are reported to be 10 times smaller, 20% more accurate, and cheaper to run than the previous generation [48]. SpaCy supports online learning, so the entity recognizer can be updated with new examples using an existing available pre-trained statistical model.

The spaCy NLP models, especially NER, follow a simple four-step formula: embed, encode, attend, and predict. First, the model receives the text and transforms the words into unique numerical values. In the embedding stage, features such as the prefix, suffix, shape, and lowercase are used to extract the similarities between the words. To encode the context-independent embeddings, the values pass through a CNN network, producing a context-sensitive sentence matrix. Before the prediction, the matrix has to pass through the CNN Attention layer to be converted into a single vector. Then, a standard Multi-layer Perceptron (MLP) with a Softmax layer is used as a tag decoder layer for class prediction. After the training process, the spaCy model is ready for several NLP tasks.

4.2. BLSTM-CRF Component

The BLSTM-CRF component in HELD is the one in charge of learning how to disambiguate the finegrained entities present in the Police reports. In other words, while the NER component only recognizes the entities to the super-labels in the two-level hierarchy (i.e., PERSON and LOCATION), the BLSTM-CRF must recognize and disambiguate them accordingly to their actual fine-grained labels (i.e., the PERSON and LOCATION sub-labels). As previously mentioned, the input for the Disambiguation Mask is the combined output of these two main components.

In the setting of sequence labeling for NER, our BLSTM-CRF component first feeds word-level representations into a BLSTM layer to encode context information of each word. On top of the BLSTM, a sequential CRF layer takes context into account to decode labels for the whole sentence jointly. In the following sections, we describe in detail the architecture of this deep learning model.

4.2.1. Word-Level Representation

³⁹ Using as the input, traditional word embeddings can capture semantic and syntactic properties of ⁴⁰ words, which do not explicitly present in the input text. We consider two types of non-contextualized ⁴¹ word-level representations in this research: (a) domain-specific or (b) pre-trained word embeddings. We ⁴² call domain-specific word embeddings the word vectors that have their weights randomly initialized ⁴³ in the word embedding layer by using a vocabulary to map the integer indices from the training set

⁴https://v2.spacy.io/api/entityrecognizer

data to dense vectors. Iteratively, during training, these word vectors are gradually adjusted via back-propagation, structuring the space into something the model can exploit. Once fully trained, the domain-specific embedding space will show a structure specialized for the problem.

For the pre-trained word embeddings, we consider those available in online repositories, typically trained over large collections of text reflecting a wider domain, such as FastText, GloVe, Wang2Vec, and Word2Vec. By using a domain-specific dataset, we can face an out-of-vocabulary (OOV) problem, which happens when some words from our data do not exist in the pre-trained word embeddings vocabulary. To handle this, we use the Levenshtein Edit Distance metric, since we do not have a vector representation for these words (i.e., domain-specific or misspelled words). Also, we want to ensure that the position of similar words in the high-dimensional space can remain the same or improve during training, in order to achieve a consistent domain-specific representation.

Specifically, the word embedding layer of the BLSTM-CRF component converts each word $x_i \in s$ into a real-valued d-dimensional vector w_{x_i} with a fixed size d via embedding matrix $W \in \mathbb{R}^{dx|V|}$. Concerning the pre-trained word embeddings only, we first replace each OOV x_i in the input text with another word with the minimum edit distance value to x_i from the pre-trained word embedding vocabulary. Then, we manually pass via embedding matrix the final pre-trained vectors. In our context, we state that the Police reports do not exceed a constant number of words M. Thus, for a given number of Police reports N received as input, we have a $(M * d) \times N$ dimension matrix as the output of the word embedding layer. The Police reports with fewer than M words are padded at the end. The output matrix will then feed into the BLSTM layer.

4.2.2. BLSTM for Context Encoder with a CRF Decoder

The BLSTM-CRF component must capture the context dependencies, taking into account the local context of each embedded word to predict labels for the tokens in the input sequence. For many sequence labeling tasks, it is beneficial to have access to both past (left) and future (right) contexts. However, LSTM's hidden state takes information only from the past, knowing nothing about the future. An ele-gant solution is bidirectional LSTM (BLSTM), which consists of using two regular LSTM layers. Each LSTM layer processes the input sequence in one direction (chronologically and anti-chronologically) and then merging their representations. By treating a sequence in both ways, a BLSTM can catch patterns that may be missed by the chronological-order version alone. To capture such contextual information, we use a stacked BLSTM layer.

For prediction, it is beneficial to consider the correlations between labels in neighborhoods and jointly decode the best chain labels for a given input sequence [39]. For example, consider a category of generic entity labels, such as PERSON, LOCATION, and ORGANIZATION. It is known that a token that iden-tifies an ORGANIZATION cannot follow a PERSON token. Having this in mind, we use a Conditional Random Fields (CRF) statistical model as the tag decoder. The output vectors of the BLSTM layer are fed into a CRF layer to jointly decode the best sequence of labels, focus on sentence-level instead of individual positions. CRFs takes context into account, and it is powerful to capture label transition dependencies when adopting word embeddings, producing a higher accuracy performance in general [1, 12].

Eq. (1) formalizes the combination of a BLSTM neural network with a CRF model. Let v = $\{v_1, \dots, v_T\}$ be some observed input data sequence, in our case, the output vector of BLSTM. Let S be a set of FSM (Finite State Machine) states, each of which is associated with a label, $y_i \in L$. Let $s = \{s_1, \dots, s_T\}$ be some sequence of states (the values on T output nodes). CRF defines the condi-tional probability of a state sequence given an input sequence to be P(s|v), where Z_v is a normalization factor, $f_k(s_{t-1}, s_t, v, t)$ is an arbitrary feature function over its arguments, and λ_k is a learned weight for

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each feature function. Feature functions can ask powerfully arbitrary questions about the input sequence, including queries about previous words, next words, and conjunctions of all [49]. For further details, we refer the reader to [49, 50].

$$P(s|v) = \frac{exp(\sum_{t=1}^{T} \sum_{k} \lambda_k f_k(s_{t-1}, s_t, v, t))}{Z_v}$$
(1)

4.3. Disambiguation Mask

The Disambiguation Mask component is in charge of assigning the final fine-grained labels to the input tokens. For this task, the Disambiguation Mask combines the outputs of the NER and BLSTM-CRF components by performing a pairwise decision. Both main components in HELD identify approximately the same-named entities, dealing with them in different ways. Within this context, review Figure 1 which illustrates HELD. Given an input token x_i , for each pair of outputs, the Disambiguation Mask first looks at the NER component output. The NER component recognized x_i with a super-label $e_i \in E$, where E is the set of super-labels. Then, together with the output of the BLSTM-CRF component, in this case, the marginal probability distribution of the fine-grained labels $P(y_i) = [p(l_1), p(l_2), \cdots, p(l_C)]$, where $p(l_i) \in [0,1] \ \forall \ l_i \in L$, the Disambiguation Mask assigns for the input token x_i , the label l_i that has a higher probability, given that l_i is the sub-label of e_i . Eq. (2) formalizes our Disambiguation Mask, i.e., how a given input token x_i is assigned to its final label y_i . 2.2

$$y_i = Max\{[p(l_1^{e_i}), p(l_2^{e_i}), \cdots, p(l_c^{e_i})]\}$$
(2)

5. Experimental Evaluation

In this section, we discuss the experimental evaluation. The main research questions that guide this study are:

RQ1 How effective is the NER component at recognizing the named entities in Police reports into the super-labels of the hierarchical structure present in our fine-grained entity labels?

For this research question, we explore the two possible usage versions of the spaCy NER. One version has the available pre-trained entity recognizer model trained on a large corpus, while the other version concerns the update (fine-tuning) of the pre-trained spaCy NER with our data. We aim at evaluating how these versions perform for the Police domain in the super-labels recognition.

RQ2 What is the best word-level representation for the BLSTM-CRF component that most effectively captures the semantic properties of the Police report's vocabulary?

This research question investigates the best input word representation for the BLSTM-CRF component. We present the performance of the BLSTM-CRF model on different pre-trained word embeddings: FastText, GloVe, Wang2Vec, and Word2Vec. We also generate domain-specific word embeddings using the training set data, mapped through a domain-specific vocabulary with almost 400,000 tokens.

3 4 5 6 7 8	With this research question, we want to compare the performance of our proposed model against some baselines. Through the experimental results, it will be possible to have a better clue of the importance of each proposed component in the architecture.	2 3 4
4 5 6 7 8	some baselines. Through the experimental results, it will be possible to have a better clue of the importance of each proposed component in the architecture.	4
5 6 7 8	importance of each proposed component in the architecture.	
6 7 8	importance of each proposed component in the arcintecture.	5
7 8		6
8	Note that these three research questions, previously defined by domain experts, are complementary	7
0	to each other and follow the architecture of Figure 1. In the following sections, we discuss the schemes	, 8
Q	designed to answer them. We first introduce the dataset used in the experiments, report the experiment	a
10	setups, and finally discuss the results.	10
11		11
12	5.1. Dataset Construction	12
13		13
14	To evaluate our proposed method, we use a real dataset with texts from Police reports. In contrast	14
15	to other domain-specific datasets, to our best knowledge, there is no available annotated dataset for the	15
16	Police domain.	16
17	Data annotation. We use our interactive framework HNERD (Human Named Entity Recognition with	17
18	Deep Learning) [47] to create a manually annotated dataset. Despite being a complete tool to assist	18
19	the user in NER classification tasks. HNERD was used only for the annotation process. The annotated	19
2.0	corpus contains a total of 3.083 real narrative reports written in Portuguese describing the homicides in	20
21	the city of Fortaleza (Brazil) from 2014 to 2020.	21
2.2	Data annotation remains time-consuming and expensive. It requires domain experts to perform inten-	2.2
23	sive annotation tasks. A total of nine domain experts were responsible for hand-labeling the data with	23
24	HNERD. The manually annotated dataset was based on a less fine-grained annotation scheme with five	24
25	labels:	25
26		26
27	(i) VICTIM, a named victim;	27
28	(ii) PARENTS, the names of the victim's parents;	28
29 30	(iii) INVOLVED, the names of any other person mentioned in the narrative, other than VICTIM or PARENTS:	29 30
31	(iv) LOC DEATH the name of victim's death location: and	31
32	(iv) LOC DES the name of victim's residence leastion	32
33	(v) LOC_RES, the name of victim s residence location.	33
34	The two corresponding super-labels in the two-level hierarchy present in the fine-grained labels are:	34
35	PERSON which covers the labels VICTIM PARENTS and INVOLVED and recognizes a named	35
36	person or family: and LOCATION, the names of politically or geographically defined location (i.e.,	36
37	names or addresses of public or private spaces cities provinces countries bodies of water mountains)	37
38	covering the labels LOC DEATH and LOC RES Also we use the O (OTHER) label to indicate non-	38
39	entity tokens	39
40	Labels statistics. The annotated corpus contains a total of 23.837 named entities (per-token basis) with	40
41	10.960 mentions to VICTIM, 6.516 to LOC, DEATH, and 5.377 to INVOLVED. These first three fine-	41
42	grained labels representing the group of the most frequent entities, the majority labels. For the group	42
43	of the rarest or minority labels, we have 512 mentions to LOC RES and 472 to PARENTS As we can	43
44	observe, the distribution of our dataset faces a data imbalance problem that occurs when some labeled	44
45	entities appear much more than others.	45
46		46

We follow the iterative stratification technique proposed by [51] to provide the official training (60%), development (20%), and test (20%) sets, using the same seed for the split of our multi-label corpus, which has several target labels per text. Since we are dealing with a sequence labeling task, the iterative stratification manages to output a proportional sample of labels in the three sets to prevent measurement errors for the data imbalance issue. After the split, the training set remained with a total of 1,833 texts, while the development and test sets both with 625 instances each. The per-token named entities distribution for each subset is reported in Table 1.

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т	T	Table 1	a man talı		
I Super label	Labol	distribution	Set	s	
Super-label	Laber	Corpus	Train	Test	Dev
	VICTIM	10,960	0.465	0.453	0.451
PERSON	PARENTS	472	0.020	0.019	0.021
	INVOLVED	5,377	0.224	0.228	0.227
LOCATION	LOC_DEATH	6,516	0.269	0.276	0.283
LOCATION	LOC_RES	512	0.021	0.025	0.019

5.2. Experiment Setup: Training Process, Evaluation Metrics, and Baseline Models

NER component training process. We use the following steps to train the NER component in HELD. 2.2 First, all spaCy models support online learning, so we load an existing pre-trained model available for the Portuguese language⁵. Then, we disable all the other pipeline components to retrain only the spaCy entity recognizer. After defining the labels (in this case, PERSON and LOCATION) and the epochs for training, we loop over our training set annotated with the super-labels⁶. During the loop, we update the model to steps through the words of the input. At each word, the spaCy NER makes a prediction and then consults the annotations to see whether it was right; if it was wrong, it adjusts its weights so that the correct action will score higher next time [48]. For each epoch, we test the retrained model using the development set to make sure that the entities in the training data are correctly recognized.

BLSTM-CRF component training process. We use our training set annotated with the fine-grained labels to train the BLSTM-CRF component in HELD. Similar to the NER component training process, for each epoch, we assess the accuracy of the BLSTM-CRF model using the development set. We also use an early stop strategy to stop the training phase if the accuracy of the model on the development set is not improving. For comparative purposes, we train the model with three distinct loss functions: Class-Balanced (CB) loss [52], Dice loss (DL) [22], and CRF loss [50]. The CB and Dice losses are widely used heuristics that deal with the label imbalance issue, while the CRF loss is often required in models for sequential labeling tasks that have a CRF layer as a tag decoder. Specifically, the CRF loss decides a proper loss (e.g., Categorical Cross-Entropy, Sparse Categorical Cross-Entropy, etc.) for the CRF layer learning mode. By addressing cost-sensitive learning solutions to deal with the data imbalance problem is expected that BLSTM-CRF must be able to achieve a significant increase in performance.

- ⁵https://v2.spacy.io/models/pt

⁴⁴
⁶For the NER component training process, we replace the annotated fine-grained labels in our dataset with only the superlabels. This experimental procedure is explained in Section 5.3.

The CB loss can be applied as a generic loss to a wide range of deep learning models and loss functions. This version considers exactly one label per sample [52], so we had to adapt it to deal with multilabel data. Our adaptation assigns each sentence token to one of the mutually exclusive classes, which corresponds to the Categorical Cross-Entropy (CCE) loss [53]. We replace the loss function \mathcal{L} in the CB loss formula with the CCE loss, leading to the Categorical Cross-Entropy Class Balancing (CB-CCE) loss to substitute the generic CB loss.

Evaluation metrics. The evaluation metrics used in the experiments are Precision (P), Recall (R) and F₁-score (F_1) , defined by Eq. (3-5). They are widely used for an exact-match evaluation of NER systems, where a correctly recognized instance requires a model to correctly identify its boundary and label, simultaneously [1]. The numbers of false positives (FP, recognized entities that do not appear in the ground truth), false negatives (FN, not recognized entities that appear in the ground truth), and true positives (TP, recognized entities that also appear in the ground truth) are used to compute Precision, Recall, and F₁-score, given as follows:

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$$\mathbf{P} = \frac{TP}{TP + FP} \qquad \qquad \mathbf{R} = \frac{TP}{TP + FN} \qquad \qquad \mathbf{F}_1 = 2 \cdot \frac{\mathbf{P} \times \mathbf{R}}{\mathbf{P} + \mathbf{R}} \qquad \qquad (3, 4, 5)$$

This work focuses on the token-level method evaluation for all the tested models in this experimental procedure. The metrics P, R, and F₁ are used to compute each label individually, considering that each input token present in the corpus has a label assigned to it. In addition, the macro-averaged of the empirical metrics values considers the performance across multiple entity labels. Macro-averaging treats all the recognized entities as equal to provide a realistic calculation since we do not have a large number of imbalanced entity labels. Consider a metric M chosen to measure the performance of each labeled entity, the macro-averaged $M(M_{macro})$ independently calculates the M on different entities, then takes the average of the M's. For a labelset L with the size |L|, the M_{macro} is given as follows:

$$M_{macro} = \frac{1}{|L|} \sum_{l=1}^{|L|} M_l,$$
(6)

Baselines. We compare HELD against two baselines. All the models are trained and evaluated using the same training, development, and test stratified data as used by the HELD model. Notice that these base-lines are the isolated components of HELD. Nevertheless, these components, individually, represent state-of-the-art architectures for solving NER tasks. Thus, in the context of fine-grained label disam-biguation in Police reports, we want to evaluate how the ensemble architecture of HELD outperforms these two common approaches used in NER.

• spaCy NER (spaCy): We use the pre-trained spaCy NER model [48] available for Portuguese finetuned on our training set annotated with the fine-grained labels. The idea here is to compare how a NER solver performs on our Hierarchical Entity-Label Disambiguation problem.

• BLSTM-CRF: In [46], we developed a deep learning model called Char-BLSTM-CRF, which achieved high performance on tackle the label or class disambiguation problem in Police reports documents. In the present work, we designed the BLSTM-CRF component of HELD based on the Char-BLSTM-CRF model. Char-BLSTM-CRF incorporates character-based word representations

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extracted by an LSTM neural network, so we removed the character-level layer since we deal with OOV words differently. Therefore, we only use word-level embeddings as input for the BLSTM-CRF recognition baseline model. This model was implemented using the Keras library [54] with TensorFlow in the backend.

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Computational resources. All models listed in our experiments were implemented and run on Colab⁷, a product from Google Research. Colab is a hosted Jupyter Notebook service that requires no setup to use. In particular, we use TPUs to run the BLSTM-CRF models, one of Colab's free computing resources. For spaCy models, we ran using Colab's CPU. SpaCy v2.0 does not support TPUs, and the GPU runtimes, at least in our experiments, did not provide faster training.

Model notation. For the experimental procedure and results, we use the two following notations: (i) $MODEL_{<embedding>}^{<loss>}$, where MODEL refers to the deep learning approach used (i.e., BLSTM-CRF or HELD), and the indexes *embedding* and *loss*, corresponding to the word-level embedding representation and the loss function used for training, respectively; (ii) *spaCy*_{<method>}, where the index *method* identifies for the spaCy NER tool whether we are using its *pre-trained* or *fine-tuned* (with our training data) version.

¹⁷ 18 5.3. RQ1: Evaluating the Performance of the NER Component

Our experimental results for the RQ1 over the test set are summarized in Table 2.

Usage setups. We assessed the two possible usage setups of the spaCy NER: $spaCy_{pre-trained}$ and spaCy_{fine-tuned}. The first one refers to the pre-trained available NER model that recognizes the following entities: PER (PERSON), LOC (LOCATION), ORG (ORGANIZATION), and MISC (MISCELLANEOUS), trained with the Universal Dependencies (UD) Portuguese treebank and WikiNER corpora [48]. In turn, spaCy_{fine-tuned} refers to the fine-tuning of $spaCy_{pre-trained}$ with our training data annotated with the labels PERSON and LOCATION. Both usage setups took about 2 to 3 hours of training.

Data annotation format. To retrain the *spaCy_{pre-trained}*, we replace the fine-grained labels annotated in
 our stratified subsets (train, test, and development) to be tagged only with the super-labels. Therefore,
 the mentions of VICTIM, PARENTS, and INVOLVED were replaced by PERSON, and the mentions of
 LOC_RES and LOC_DEATH became LOCATION.

The performances of	spaCy NEF	Tab pre-traine	ole 2 d and fine-t	uned mode	ls for the su	ıper-label
Supar labal	sp	aCy _{pre-train}	ned	sp	aCy _{fine-tur}	ned
Super-label	Р	R	F ₁	Р	R	F ₁
PERSON	0.1819	0.1289	0.1509	0.9467	0.9382	0.9424
LOCATION	0.1399	0.1634	0.1507	0.6275	0.6719	0.6489
Macro-averaged	0.1609	0.1462	0.1508	0.7871	0.8051	0.7957

³⁹ **Discussion.** *SpaCy*_{*fine-tuned*} shows better performances in all three metrics for the two super-labels, reach-⁴¹ ing a macro F₁-score equal to 0.7957. Interestingly, *spaCy*_{*pre-trained*} achieves a limited performance in this ⁴² experiment, with similar F₁-score values for PERSON and LOCATION (slightly difference of +0.0002), ⁴³ and a macro F₁-score of 0.1508. We believe that the spaCy model only trained on UD Portuguese tree-⁴⁴ bank and Wikipedia corpora perform inconsistently due to the specificities of our Police domain. Also,

⁷https://colab.research.google.com/

by fine-tuning the pre-trained NER model only for the super-labels PERSON and LOCATION, skipping ORG and MISC, the model seems more effective in learning to identify and classify named persons and locations. The F_1 values for *spaCy*_{fine-tuned} results are consistent with the total number of samples for each super-label in our dataset since we have more mentions for PERSON (higher F_1 of 0.9424, recognizing almost all mentions for this entity) than LOCATION (F_1 of 0.6489).

⁶ We observed by addressing RQ1 that the $spaCy_{fine-tuned}$ is more effective in recognizing the named ⁷ entities present in Police reports into the super-labels of the hierarchical structure present in our fine-⁸ grained entity labels. Our experiments showed that this fine-tuned version significantly outperformed ⁹ the $spaCy_{pre-trained}$ model for the Police domain. To conclude, $spaCy_{fine-tuned}$ is the best setup for the NER ¹⁰ component in HELD.

5.4. RQ2: Evaluating the Best Word-Level Representation for the BLSTM-CRF Component

With the most effective spaCy NER model setup identified for the NER component, following the architecture of HELD, we focus here on the RQ2 to investigate the best word-level representation for the BLSTM-CRF component. We make the following observations before discussing the results of Table 3: Input setups. Since our dataset contains documents written in Portuguese, to train the domain-specific word embeddings we use the same corpus vocabulary used in our previous work [55], which has 393,550 tokens collected from Police reports from Fortaleza (Brazil) from 2010 to 2018. Concerning the pre-trained word-level embeddings, we use the vectors generated by FastText, GloVe, Wang2Vec, and Word2Vec models that were trained on seventeen linguistic corpora of Brazilian and European Portuguese, from different sources and genres, corresponding to more than one trillion tokens [56]. These pre-trained versions are available on the NILC repository⁸, and we selected the ones that were trained with the Skip-Gram architecture since it gives a better representation of rare words and is more indicated to identifies patterns [57]. Both pre-trained and domain-specific word embeddings have an embedding size of 50 dimensions.

Specifically, we evaluate three different input setups for the word embedding layer: *domain-specific*,
 pre-trained, and *concat*. The *domain-specific* version learns word embeddings for our Police domain
 jointly with the BLSTM-CRF model training, while the *pre-trained* version uses the original pre-trained
 vectors (from FastText, GloVe, Wang2Vec, and Word2Vec) fixed during training. Lastly, the *concat* (i.e.,
 a concatenation layer) concatenates both the *domain-specific* and the *pre-trained* vectors.

Missing words. For what concerns the statistics of our dataset, the number of tokens in a sentence varies from 6 to 537. We observe that 50% of the sentences have 32 tokens or less, while 75% of the dataset have 49 tokens or less. By looking at the effectiveness of *domain-specific* version, in 50% of sentences domain-specific embedded 31 tokens per sentence or less. While for 75% of the dataset, domain-specific word embeddings represented 49 tokens per sentence or less. When we used the pre-trained version as a word embedding layer, 30 tokens per sentence or less were embedded for 50% of sentences. While for 75% of the dataset, pre-trained word embeddings represented 47 tokens per sentence or less. The differences between the percentiles are slight, which indicates that the level of missing tokens for sentences embedded by *domain-specific* and *pre-trained* are minimal.

Discussion. In more detail, each row in Table 3 represents a word-level embedding representation and
 a loss function. We evaluate the performance of the BLSTM-CRF model by training it with nine word-level representations (i.e., one *domain-specific*, four *pre-trained*, and four *concat* versions) and three loss

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⁸http://nilc.icmc.usp.br/nilc/index.php/repositorio-de-word-embeddings-do-nilc

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				Table 3							
The general performances of the BLSTM-CRF variations.											
<word-level blstm-crf<sup="">CB-CCE</word-level>				BLSTM-CRF ^{CRF}			BLSTM-CRF ^{DL}				
embedding>	P macro	R macro	F _{1 macro}	P macro	R macro	F _{1 macro}	P macro	R macro	F _{1 macro}		
Domain-specific	0.411	0.580	0.455	0.471	0.473	0.469	0.462	0.440	0.447		
FastText	0.530	0.778	0.611	0.709	0.556	0.603	0.598	0.522	0.554		
GloVe	0.557	0.763	0.629	0.712	0.565	0.598	0.475	0.436	0.453		
Wang2Vec	0.561	0.739	0.619	0.744	0.580	0.638	0.491	0.425	0.452		
Word2Vec	0.486	0.767	0.574	0.733	0.574	0.614	0.473	0.460	0.465		
ConcatFastText	0.431	0.686	0.491	0.565	0.602	0.581	0.591	0.574	0.580		
ConcatGloVe	0.469	0.638	0.521	0.560	0.595	0.576	0.486	0.501	0.492		
ConcatWang2Vec	0.458	0.625	0.509	0.574	0.551	0.556	0.500	0.470	0.483		
ConcatWord2Vec	0.457	0.654	0.508	0.575	0.554	0.562	0.524	0.510	0.508		
	0.107	0.051	0.200	0.575	0.001	0.502	0.521	0.010	0.20		

functions (i.e., CRF, CB-CCE, and DL). All the BLSTM-CRF model variations were trained in 4 to 5 hours.

The BLSTM-CRF $_{Wang2Vec}^{CRF}$ model had the best performance with a macro F₁-score equal to 0.638. In general, the performance of the models using the *pre-trained* setup for the word embedding layer outperform the two other versions: domain-specific and concat. In this case, the domain-specific word embeddings had the worse average performance ($-0.191 \text{ macro } F_1 \text{ vs. } BLSTM-CRF \frac{CRF}{Wang2Vec}$). The results suggest that the corpus is not large enough for representing the relationship between the words used in the Police reports. Besides, the fact that the *concat* representation under-performs the *pre-trained* one 2.2 suggests that the *domain-specific* layer in the *concat* setup added noise to the model. *Domain-specific* and pre-trained have different representations and, therefore, different vector spaces. When we concatenate different vectors, the scales of the word embeddings may not be the same and neither the dimensional training space. We similarly experiment with the BLSTM-CRF models by *fine-tuning* the pre-trained word embeddings but performed poorly.

Two main observations are obtained from this experiment. First, the performance of the BLSTM-CRF model does not necessarily have just one specific best word embedding representation for all the loss functions. In fact, even though that BLSTM-CRF ^{CRF}_{Wang2Vec} shows the best overall performance, this model achieves minor improvements (+0.009 macro F_1) compared to *BLSTM-CRF* ^{CB-CCE}_{GloVe}. As a result, Wang2Vec pre-trained vectors yielded good performance across our evaluations, particularly for the CRF and CB-CCE losses. Second, the use of loss functions that take into account the imbalance characteristics of the dataset had no relevant impact on the performance of the BLSTM-CRF model.

A closer examination of the BLSTM- $CRF_{Wang2Vec}^{CRF}$ performance is reported in Table 4 for each label individually. The label that the model performs best is VICTIM (F_1 of 0.875), which is the label with the largest number of samples in the dataset. The most difficult label for recognition is LOC_RES (F_1 of (0.329). For the PARENTS label, even with the smallest proportion of samples, the model achieves an F_1 value of 0.599, a higher value than that obtained for LOC RES. Most likely due to common expressions found in the text that help to recognize PARENTS, such as "son of ...", "daughter of ...", or even "having as a father [...] and mother [...]".

In conclusion, the pre-trained word-level representation generated by the Wang2Vec Skip-Gram model most effectively captures the semantic properties of the Police report's vocabulary. We also observe that the use of domain-specific embeddings from our training data has not improved consistently the performance of the models. It may suggest the need of a larger corpus for the domain. By addressing

Table 4 of <i>BLSTM-CRF</i> ^{CRF} _{Wang2}	_{Vec} for each	n label inde	ependently			
Super label Label BLSTM-CRF Wang.					BLSTM-CRF CRF Wang2V	RF Vang2Vec
Label	Р	R	F1			
VICTIM	0.868	0.883	0.875			
PARENTS	0.658	0.549	0.599			
INVOLVED	0.769	0.624	0.689			
LOC_DEATH	0.798	0.618	0.696			
LOC_RES	0.628	0.223	0.329			
	Table 4 of BLSTM-CRF ^{CRF} Wang2 Label VICTIM PARENTS INVOLVED LOC_DEATH LOC_RES	Table 4of BLSTM-CRF CRF Wang2Vecfor eachLabelBLSTMVICTIM0.868PARENTS0.658INVOLVED0.769LOC_DEATH0.798LOC_RES0.628	Table 4f BLSTM-CRF $^{CRF}_{Wang2Vec}$ for each label indexBLSTM-CRF $^{C}_{W}$ LabelBLSTM-CRF $^{C}_{W}$ P R VICTIM0.8680.883PARENTS0.6580.549INVOLVED0.7690.624LOC_DEATH0.7980.618LOC_RES0.6280.223			

the RQ2, the best setup for the BLSTM-CRF component in HELD is the *BLSTM-CRF* ^{CRF}_{Wang2Vec} model.
 This model performance demonstrates the effectiveness in recognizing the fine-grained entity labels on
 Police narrative reports.

16 5.5. RQ3: Assessing the Improvement of HELD

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We continue our experiments focusing on the last research question. To address RQ3, we finally investigate the performance of our proposed ensemble architecture: HELD. Our experimental results are reported in Table 5.

Best setups. To compose the architecture of HELD, we use the best setups of each component. We use BLSTM- $CRF_{Wang2Vec}^{CRF}$ for the disambiguation of the fine-grained labels, and the $spaCy_{fine-tuned}$ for the super-labels recognition. We compared the performance of our ensemble architecture against each component working individually to solve the Hierarchical Entity-Label Disambiguation problem. In particular, we want to evaluate how HELD performs in confront to $spaCy_{fine-tuned}$ and BLSTM- $CRF_{Wang2Vec}^{CRF}$ for the recognition of fine-grained entities in Police reports. The $spaCy_{fine-tuned}$ model that recognizes fine-grained entity labels took about 2-3 hours to train.

Table 5

29 The performances of HELD and the baseline models. 30 HELD^{CRF} Wang2Vec BLSTM-CRF CRF Wang2Vec spaCy_{fine-tuned} 31 Super-label Label P P R F₁ P R F_1 R \mathbf{F}_1 32 VICTIM 0.431 0.697 0.535 0.868 0.883 0.875 0.849 0.909 0.871 33 PERSON PARENTS 0.799 0.789 0.694 0.405 0.498 0.449 0.618 0.696 0.613 34 INVOLVED 0.103 0.273 0.152 0.769 0.624 0.689 0.723 0.697 0.708 35 LOC_DEATH 0.333 0.333 0.333 0.628 0.223 0.329 0.448 0.421 0.436 36 LOCATION LOC RES 0.122 0.158 0.115 0.658 0.549 0.598 0.644 0.516 0.573 37 38 0.279 0.392 0.317 0.744 Macro-averaged 0.580 0.638 0.656 0.666 0.656 39

⁴⁰ **Discussion.** HELD shows the best performance overall, as demonstrated by its highest macro F_1 -score ⁴¹ equal to 0.656. Compared with *spaCy_{fine-tuned}*, HELD shows better performances for all labels, which ⁴² demonstrates that this classic NER tool alone is not capable of performing efficient disambiguation ⁴³ on the fine-grained entity labels. Compared with the *BLSTM-CRF* $_{Wang2Vec}^{CRF}$ deep learning model, HELD ⁴⁴ shows the higher F_1 for INVOLVED and LOC_DEATH (F_1 values of 0.708 and 0.436). The *BLSTM-*⁴⁵ *CRF* $_{Wang2Vec}^{CRF}$ model is the more challenging baseline, with a macro F_1 -score of 0.638, and reaching the

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best F₁ for VICTIM (0.875) and the rarer entity labels (PARENTS with an F₁ of 0.696 and LOC_RES with 0.598). However, it is also worth noting that the difference between the F₁ values for VICTIM, PAR-ENTS, and LOC_RES is very low for HELD and BLSTM-CRF CRF (-0.004, -0.002 and -0.025, respectively). In summary, in RQ3, we have assessed that by combining the BLSTM-CRF and spaCy NER models in an ensemble architecture, it allows HELD to exploit the best of each model to improve the fine-grained classification in Police reports of the named entities recognized as the super-labels of our twolevel hierarchical structure. The important conclusion here is that our approach can leverage the NER component (i.e., spaCyfine-tuned updated with the super-labels) to disambiguate the entity mentions based

6. Conclusions and Future Work

on the context.

This paper has presented HELD, an ensemble model for the Hierarchical Entity-Label Disambigua-tion problem in Police reports. This problem is very challenging since the fine-grained entities must be recognized and disambiguated in the narrative reports based on the sentence context. To the best of our knowledge, we believe that our work is the first to tackle such a problem. Our ensemble approach is domain-independent, which ensures that it can be applied in various domains as long as it has texts with ambiguous entities arranged in a hierarchical structure. HELD is free from knowledge bases, languagespecific resources, and hand-crafted features, and includes two main components for sequence labeling in NER: a NER component represented by the spaCy NER tool and a BLSTM-CRF component. Each component has a specific task: spaCy NER identifies and classifies only super-labels from a two-level label hierarchy, and the BLSTM-CRF model recognizes and disambiguates fine-grained entity labels. HELD combines the predictions of the spaCy NER and BLSTM-CRF models via Disambiguation Mask to assign the final fine-grained labels for the input texts.

We train HELD and the baseline models using a real corpus of Police reports human-annotated in the HNERD framework. To guide our experimental evaluation, we address three research questions. The first research question explored the most effective spaCy NER model setup for the NER compo-nent. The spaCy_{fine-tuned} model, which is the retrained spaCy_{pre-trained} model with our annotated data only with super-labels, can correctly recognized about 80% more super-labels according to our experimental results. The second research question focused on the discussion on the best word-level representation for the BLSTM-CRF component. We evaluated three different input setups for the word embedding layer of this component (domain-specific, fine-tuned, and concat), and we also test different training loss functions (CRF, CB-CCE and DL). The most effective deep learning model identified in evaluation experiments was the BLSTM-CRF CRF Wang2Vec model. Finally, for the third research question, we compared the performance of our proposed model with two baselines that are the isolated components of HELD. Compared with the *spaCy*_{fine-tuned} and *BLSTM-CRF* $_{Wang2Vec}^{CRF}$, a major advantage of HELD is the ability to improve the fine-grained classification in Police reports of the named entities recognized as the super-labels. Evaluation experiments demonstrated that our proposal outperforms the baselines in terms of quality.

Several directions could be pursued to expand this research. First, a research direction would be to
 explore active learning techniques to reduce the effort of the data annotation process. Second, we can
 further enhance the performance of HELD by testing other state-of-the-art approaches. Our main interest
 is in the recent language models, such as BERT, GPT, ELMo, and Flair Embeddings, to improve the

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BLSTM-CRF component. We can attach the BLSTM-CRF model on top of the pre-trained language model to predict the labels of each token independently by fine-tuning the model for our domain. Thus, for the NER task, the contextualized language model will have the role of context encoder, besides given contextualized word-level representations. However, to do this, we have to generate a larger annotated Police reports corpus. Also, with more data available, we can increase the number of labels for our fine-grained annotation scheme. Third, another future direction is to explore different loss functions, such as the variations of the Dice Loss [22], or data level strategies for our data-imbalanced dataset. Further, we can explore data-augmentation techniques, such as word-embeddings substitution [58, 59] and masked language model applied by Transformer models, to generate additional synthetic data using the Police reports corpus. Augmentation methods are widely used approaches in computer vision applications, and they are just as powerful for NLP. For our context, they can help generate more labeled data and deal with the data imbalance problem.

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